

# The European IST Project DAVID: A Viable Approach Toward Optical Packet Switching

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**Abstract**—In this paper, promising technologies and a network architecture are presented for future optical packet switched networks. The overall network concept is presented and the major choices are highlighted and compared with alternative solutions. Both long and shorter term approaches are considered, as well as both the wide-area network and multiple-area networks parts of the network. The results presented in this paper were developed in the frame of the research project DAVID (Data And Voice Integration over DWDM) project, funded by the European Commission through the IST-framework.

**Index Terms**—Internet protocol (IP) over wavelength division multiplexing (WDM), optical metro networks, optical packet switching (OPS), semiconductor optical amplifier (SOA)-based technology.

## I. INTRODUCTION

IN THE FUTURE communication network, the optical technology is expected to play a much stronger role not only for transmission but also for network operation. For the optical network a number of stages are foreseen with optical packet switching as the final goal.

In the short term, a relatively static usage of wavelength channels is envisaged and, thus, the potential of optical switching technologies that allow fast dynamic allocation of wavelength division multiplexing (WDM) channels are not exploited. Optical packet switching (OPS) is a longer-term strategy for net-

work evolution that exploits fast switching techniques to provide greater bandwidth efficiency, flexibility, functionality, and offer finer granularity.

With the progress done in electronics, we can naturally have the following reflection: why do we need optics when electronics are already present today cost effectively with respect to the proposed optical solutions?

One response can be the following. By increasing the bit rate the first limitations of electronics will be the power consumption and the impedance adaptation. Today this problem is overcome by using a high level of parallelism to process at a low bit rate. However, if this technique is very powerful for basic functions there are major drawbacks in case of high capacity routers: the complexity of systems is increased and the performance is degraded.

Complexity can be associated to high cost and at the functional level, the increase of the complexity pushes the constraints on the scheduler part becoming, thus, the real bottleneck. By exploiting a high level of parallelism, the switch becomes a network of small switches difficult to manage. The packet loss rate is impacted and the latency is degraded mainly because of the crossing of several first-in–first-outs (FIFOs).

Optics can fulfill this demand with less power consumption with higher robustness and simpler structure. The simplicity comes by exploiting the WDM dimension. Studies show that cost of optics is very close to the cost of electronic systems but still higher. Packaging and integration will be then the key factors which will position the optical technology as a winner technology in the future, and some constructors are working in that direction which is fundamental to go into a product.

## II. IST “DAVID” PROJECT

The data and voice integration over DWDM (DAVID) project aims at proposing a viable approach toward OPS, by developing networking concepts and technologies for future optical networks, including traffic studies and control aspects. Finally, a proof-of-concept will be delivered through a demonstrator. Partners contributing to the DAVID project are Alcatel SEL (D), Alcatel CIT (F), Research Center COM (DK), National Technical University of Athens (G), Ghent University (B), OPTO+ (now part of Alcatel CIT), University of Bologna (I), University of Essex (UK), Laboratoire de Recherche Informatique d’Orsay (F), Politecnico di Torino (I), Institut National des Télécommunication (F), BTextact Technologies (UK) and Universitat Politècnica de Catalunya (E) (for the last project year Telenor (N)

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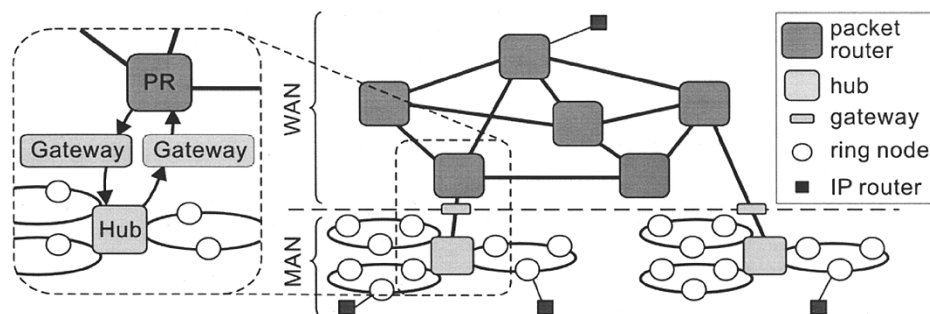


Fig. 1. DAVID network architecture.

and Telefonica (E) have joined the project to work on concept optimization, exploitation, manageability, and benchmarking).

The network architecture proposed covers both metropolitan area networks (MAN) and the wide-area network (WAN), each having a distinct structure, as illustrated in Fig. 1. In both domains, fixed-length packets are used in a slotted (synchronous) mode of operation.

The metro network comprises one or more unidirectional optical physical rings interconnected by a Hub, as discussed below. A ring within the MAN will consist of one or more fibers, each operated in dense wavelength division multiplexing (DWDM) regime, where each wavelength will be used to transport optical packets (consisting of an optical header and a payload part) having a fixed duration in time (a so-called time slot). As such, the adopted ring architecture is using both wavelength division multiple access (WDMA) and time-division multiple access (TDMA).

The ring node puts the optical packets [containing client layer traffic, e.g., Internet protocol (IP) traffic] on the ring, using a MAC protocol to decide which timeslot at what wavelength to use. Through the use of this medium access control (MAC) protocol contention is solved and the optical path within the MAN is kept bufferless.

The hub will have connection points to the MAN rings and toward a WAN optical packet router through a Gateway. The function of the hub, thus, is to interconnect rings: note that also the connection toward the WAN can be seen from a logical viewpoint as an extra ring to switch traffic to and from. Contentions between packets flowing between MAN and WAN will be solved in the Gateway.

In the WAN, a meshed network will be formed, interconnecting optical packet routers (OPRs). A link is a set of one or more fibers, each carrying multiple wavelengths. As in the MAN, the wavelengths will be used to transport optical packets of fixed time duration. The bit rate in the WAN will typically be higher carrying aggregated traffic.

### III. CONCEPT OF THE DAVID PROJECT—MOTIVATION AND CURRENT STATUS

The main motivation for migrating to optical switching is clearly to match the switching technology to the huge bandwidth capacity of WDM transmission. Moreover, optical packet switching (OPS) promises to take full advantage of available resources mainly because, compared with optical circuit switching, OPS is able to harness traffic at a much

finer granularity. An optical circuit (i.e., a single wavelength) always uses a dedicated bandwidth of 2.5, 10, 40 Gb/s or possibly even higher. This may result in a very poor filling of this bandwidth, if no efficient grooming is used. Grooming multiple client traffic streams may solve the problem, but at the price of a large number of conversions from and to electrical client layers. OPS alleviates this problem by providing smaller granularity access to the optical layer (on a packet-by-packet basis), thus avoiding the costly electro-optical conversions. In addition, the packet switching approach has also advantages with respect to resilience, as it is easier to share resources with protection schemes when a packet approach is taken compared with circuit approaches due to the use of logical paths [15] that can be created with using bandwidth.

To demonstrate the advantages brought forward by OPS, and to investigate its (technological) feasibility, several OPS test networks have been developed and evaluated [2]–[4], [7], [11].

Toward the realization of OPS, there are two principal approaches: employing fixed-length optical packets or variable length optical packets such as, e.g., optical burst switching (OBS) [16]. For fixed-length OPS, the choice remains either to operate the network synchronously using a time-slotted approach, or running it in an asynchronous manner [14]. Even though unslotted operation simplifies the implementation (e.g., avoidance of synchronization and packet alignment stages), the drawback is that link throughput is lower because contention is more likely to occur. Within DAVID, we have opted for a slotted, fixed-length packet approach, both in MAN and WAN. The advantages of fixed-length packets are numerous since all the telecom techniques (like traffic shaping, load balancing, flow control mechanisms, and traffic differentiation) can be adopted to really support a multi-CoS environment. An example of optical fixed packet size engineering can be found in [17]. The length of a time slot was set at 1  $\mu$ s for the DAVID network (both MAN and WAN).

As indicated before, the header contents will be used to control the routing of the optical packet. Different techniques to attach the header to a packet can be used: transmission on a separate wavelength, subcarrier multiplexing (SCM) (e.g., CORD [9], OPERA [7]), serial transmission of header, and payload on the same wavelength (e.g., WASPNET [3], KEOPS [1]). As this header is decoupled from the payload, its bit rate can be substantially lower than that of the payload—thereby allowing to keep the header processing in the electrical domain, as explained before. The advantage of having out-of-band headers on a separate (control) wavelength as already adopted in [18] and [16], is

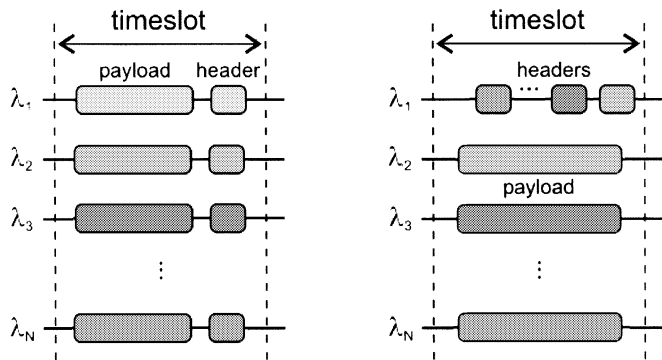


Fig. 2. Illustration of out-of-band header transportation on a separate wavelength (right) and in-band headers (left), adopted in the DAVID metro and backbone network, resp.

the capability to separate the switching plane from the control plane within the nodes together with a considerable reduction of O/E/O conversion component numbers in WAN core nodes. This is especially a viable approach in ring topologies, as the synchronization between the control and data channels is reasonably easy to maintain, as opposed to the complexity this encompasses when applied in a meshed network. Therefore, we only use the out-of-band header transportation in the metro ring network. In the DAVID backbone WAN, headers will be transported in-signal. Both approaches are shown in Fig. 2. Within DAVID, electronics are still used for header processing while the payload is switched transparently in the optical domain.

For the optical switching fabric, there are basically two options. A first is to employ a wavelength routing switch, e.g., using an array waveguide grating (AWG), where the desired output is reached by using the appropriate wavelength. This approach has been taken in WASPNET [3] and OPERA [7], but was also subject of study within KEOPS [2]. The alternative is to use a space switch such as a broadcast-and-select architecture, e.g., chosen in KEOPS. Also in DAVID, a broadcast-and-select architecture, which ensures nonblocking performance, is chosen, using semiconductor optical amplifier (SOA) technology [21], as illustrated in Fig. 3.

A major issue in every packet switched network is contention resolution. In electronic routers this problem is tackled using random access memory (RAM), which is unfeasible in the optical domain. Since all optical buffers today are technologically hard to realize, there seems to be a consensus that they should be avoided as much as possible or at least be limited to a minimum. As stated before, the MAN is completely bufferless in the optical domain. In the WAN, a shared recirculating FDL buffer is used to help solving contention, where exploitation of the wavelength domain does not suffice.

Regenerators are used to ensure sufficient cascability: an end-to-end path will of course pass through several packet switches, each one of them degrading the signal. For this, 2R or 3R all-optical regenerators have been proposed (e.g., within KEOPS), based on SOAs, which have also been successfully employed for wavelength conversion using interferometric devices based on cross-phase modulation (XPM) (e.g., in KEOPS [1], OPERA [7]).

#### IV. METROPOLITAN AREA NETWORK

The DAVID MAN consists of a number of unidirectional slotted WDM rings of metropolitan dimensions, which collect traffic from several ring nodes. These nodes provide an electro/optical interface to edge routers/switches at the end of access networks via a variety of legacy interfaces (e.g., Gigabit Ethernet in business areas, PONs in mixed or residential areas, cable head-ends, or any other legacy system).

The WDM rings are interconnected to other rings via a bufferless hub, and to a mesh of packet-switched OPRs in the core creating the complete optical WAN. The rings can be either physically disjoint, or be obtained by partitioning the optical bandwidth into disjoint portions.

The use of a hub node that is in control of the resources makes the DAVID MAN different from other optical ring networks like e.g., the HORNET (and without any limiting relation between node counts and the number of wavelength).

The hub node is used to forward optical packets between ring networks, as well as to interconnect the metro area to the backbone through an electronic Gateway. The hub is an SOA-based optical packet switch capable to cope with a very high level of traffic (Terabit/s). The lack of real optical memories is compensated through the use of an extended multiring MAC protocol. The optical hub is, thus, bufferless and its structure is similar to the one of the optical packet router in the backbone but with reduced targeted final capacity. The main difference between the hub and the OPR is at the control level: the optical hub is configured by a controller which exploits the control channels of each connected ring network, in order to calculate the switching permutation.

The hub comprises synchronization stages, a space switching stage, a wavelength switching stage, and regeneration stages if required (depending on the power budget). Each WDM channel operates at 10 Gb/s that with 32 wavelengths per ring and a channel spacing of 100 GHz, occupy 24 nm of bandwidth per ring; this corresponds to a reasonable optical bandwidth for the introduction of a SOA-based technology. The maximum capacity of one ring becomes 320 Gb/s.

Ring access nodes in the DAVID MAN are composed of an electronic part and an optical part (Fig. 4). The electronic part realizes the adaptation with client layers, which is performed in the traffic manager board (TMB). Specific burst mode transceivers (BMTs) are used to send/receive optical packets to/from the optical packet ring networks.

At the optical level, two optical packet add/drop multiplexers (OPADMs) are currently proposed in the DAVID project to propose a progressive introduction of optical packet technologies.

Targeting a short/medium term approach, a first proposal was made to limit the use of advanced optical technologies and use commercial and mature ones instead. Based on passive structures as described in [42], the architecture uses optical couplers and off-line optical filters to minimize physical issues when cascading the OPADMs [Fig. 5(a)].

A second OPADM structure is also considered as a longer-term approach allowing this erasing function [Fig. 5(b)]. It exploits wavelength bands of four wavelength each allowing a very flexible design of the OPADM with parallel small

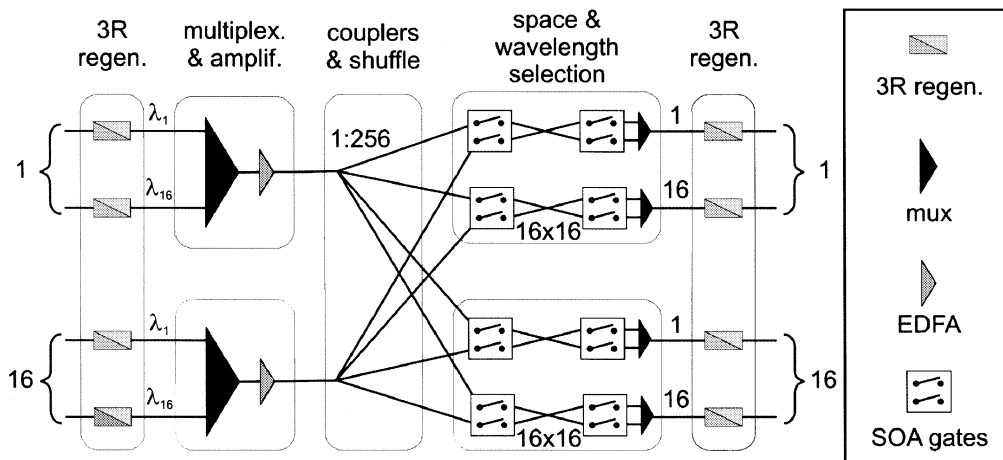


Fig. 3. Structure of the broadcast and select switch matrix adopted in DAVID.

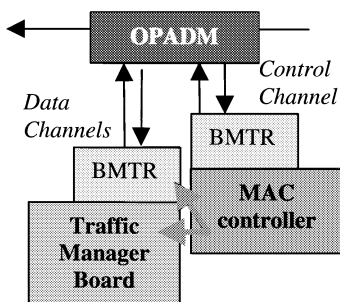


Fig. 4. Generic structure of the ring access node.

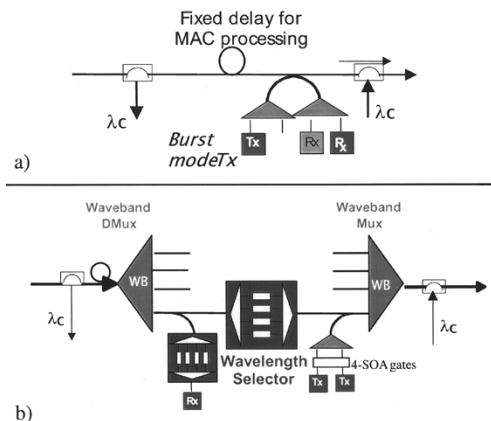


Fig. 5. Structures of the (a) passive OPADM for short-term application and (b) active OPADM for longer-term applications.

add/drop functions per waveband and limits the tunability range for the transceivers. In addition, this limits the constraints on the wavelength selector component which relies on advanced optical technology.

In the second OPADM approach, the payload receivers are tunable. The number of data transceivers can be less than the number of wavelength channels available on the ring (often one single data transceiver is considered). In this approach, the ring nodes must also have a selective erasure capability, in order to remove packets from the ring that are being received.

1) *Medium Access Control (MAC)*: The rings are shared media, requiring a MAC protocol to arbitrate access to its slots,

in order to regulate both time and wavelength dimensions. The overall system works as a combined wavelength/time/space distributed multiplexer. Contention and collision is avoided by an allocation algorithm and intelligent operation in the ring nodes using the control channel.

The slots in the control channel have a locked timing relationship to the data multislots and arrive earlier at each node by a fixed amount of time allowing for processing the contents of the control slot (and tuning time in case of tunable transceivers). Only the control channel is converted to the electrical domain for processing at each ring node, while the bulk of user information remains in the optical domain until its final destination in the end ring. The control slot information includes the state (empty or used) of the data slots, and the destination address of the corresponding data packets.

The inlet-outlet hub allocation algorithm works as follows: a measurement cycle is defined, during which the hub monitors the use of the slots allocated to any ring pair  $(i, j)$ . The monitoring of ring-to-ring traffic can be based either upon measurements of the load on the different rings at the hub, or upon explicit reservations issued by ring nodes. At the end of the measurement cycle, the hub issues a new set of switching permutations, to be used for the coming measurement cycle. The order in which permutations are generated may be of importance to smoothen as much as possible the flow entering each ring.

The hub acts as a nonblocking switch that is reconfigured in every time slot and can exploit wavelength conversion to solve contention.

The computation of the sequence of permutations operated by the Hub is a scheduling problem [22], [23], as shown in Fig. 6. Several approaches can be envisaged to solve this problem, ranging from complex optimizations to simple heuristics.

Given this hub behavior, each multislot traverses a sequence of rings, e.g., as illustrated in Fig. 7. Nodes of ring  $x$  transmit data to be received by nodes of ring  $y$  (steps 2 to 4). Ring  $x$  can be viewed as the “upstream” ring, where transmissions occur, while ring  $y$  can be viewed as the “downstream” ring, where receptions occur.

2) *A Simple Scheduling Algorithm*: A simple greedy approach to compute the scheduling at the hub is described in

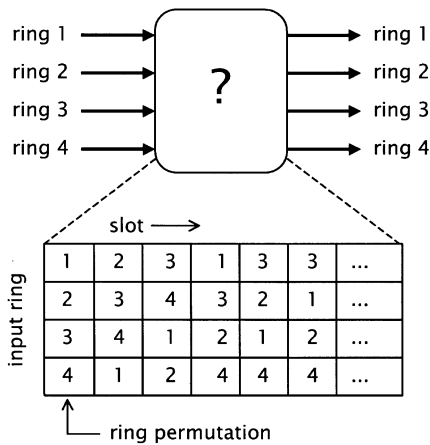


Fig. 6. Scheduling at the hub.

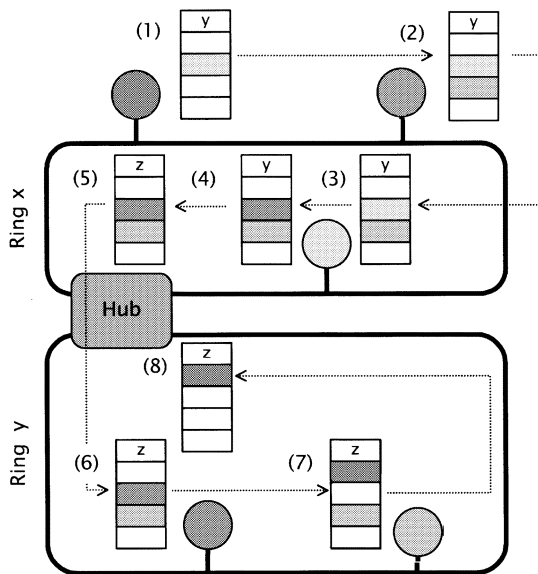


Fig. 7. Multislot forwarding in the MAN. Colors in slot represent packet destinations.

this section. The algorithm is run at the hub in a centralized fashion, and can be suited for best-effort services with no strict quality-of-service (QoS) guarantees. Only unicast traffic is considered.

Assume that, for each ring pair (upstream ring, downstream ring), an indication of the “urgency” of serving that pair is available at the hub. This information may come from measurements at the hub, or from node reservations, or it can be obtained by other ways (see Section IV-A3 on fairness control). All ring pairs are sorted by decreasing urgency.

The permutation provided in outgoing multislots is computed as follows. Since it must be a permutation, each ring can appear one time at most as upstream ring and one time at most as downstream ring. All ring pairs (ordered as above) are sequentially scanned, and the current pair is selected for the permutation if the upstream ring was not previously selected as an upstream ring, and the downstream ring was not previously selected as a downstream ring either.

Other scheduling algorithms were studied in the project (see, e.g., [25]).

3) *Fairness Control and QoS*: The proposed empty-slot operation can exhibit fairness problems under unbalanced traffic. This is particularly true in the ring topology, in which, as already mentioned, upstream nodes have generally better access chances than downstream nodes.

Credit-based schemes can enforce throughput fairness [27], such as, e.g., the Multi-MetaRing [26], which is basically a generalization of the token-ring technique: a control signal or message, called scanning acoustic tomography (SAT), is circulated in store-and-forward mode from node to node along the ring. A node forwarding the SAT is granted a transmission quota: the node can transmit up to  $Q$  packets before the next SAT reception. When a node receives the SAT, it immediately forward the SAT to the next node on the ring if it is satisfied (hence, the name SAT), i.e., if no packets are waiting for transmission or if  $Q$  packets were transmitted since the previous SAT reception. If the node is not satisfied, the SAT is kept at the node until one of the two conditions above is met. To be able to provide the full bandwidth to a single node, the quota  $Q$  must be at least equal to the number of data slots contained in one ring latency.

Another, novel QoS-sensitive MAC mechanism for slotted WDM rings based on class reservations is presented in [28]. This mechanism presents satisfactory performance with fast adaptation to a changing traffic mix, allowing for high efficiency. Other approaches, aiming at delay and bandwidth guarantees, are also being studied within the DAVID project.

## V. WIDE-AREA NETWORK (WAN)

The architecture of the WAN network is assumed to be a mesh of high capacity optical packet routers (OPRs). The mesh could rely on a virtual topology based on lightpaths in a wavelength-routed network. The OPRs are used only where high capacity is required and where the traffic can be aggregated and conditioned properly.

This overall WAN architecture is well suited to the use of GMPLS for network control, with a hierarchy ranging from conventional electrical multiprotocol label switching (MPLS) to optical MPLS and MPλS. As a result of this choice it is possible to guarantee scalability to the hierarchy according to the needs in terms of level of aggregation and capacity, support for QoS at the network level, and the tools for traffic engineering in the network.

It has already been outlined that for the DAVID network a fixed-length slotted packet format has been chosen. However, the format is different and traffic aggregation can be performed by the gateway.

Two alternatives are available when considering the management of packet slots resulting from segmentation of the same client burst. The first places a header per slot and treats any slot independently and the second treats the slots as a whole with just one header on the first slot. It results into a sort of tradeoff between a purely slotted, ATM-like network, that has already been studied in the past with reference to optical packet switches [2], [11] and an IP-based network with variable length packets. Both options are investigated within the DAVID project, the former being called fixed-length packet (FLP) and the latter slotted variable-length packet (SVLP).

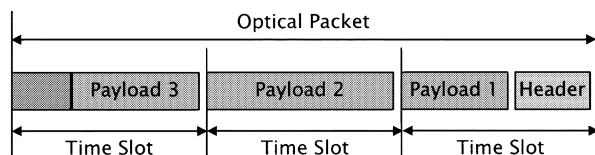


Fig. 8. Example of slotted variable length packet.

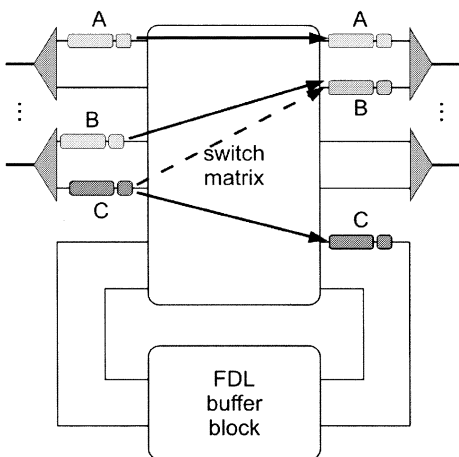


Fig. 9. Illustration of contention resolution approaches in the DAVID network.

As already mentioned above, both the wavelength domain and FDLs are used to solve the contention problem in DAVID, and is sketched in Fig. 9. A recirculating buffer is chosen, because this avoids extra switching stages/components outside the switching matrix (the buffer block only contains fiber loops). To accommodate for packet B, the wavelength domain is exploited. Packet C is redirected to the optical buffer to solve the contention.

## VI. TECHNOLOGY AND BASIC BUILDING BLOCKS

In the creation of an optical packet switch network, both optical and electronic technologies play an important role and a seamless interaction between the two technologies is needed.

### A. Optical Technology

The first challenge is probably at the concept level that must be attractive enough in terms of performance and cost to force a standard on an optical packet format. Linked to the packet format, two building blocks are mandatory: the interface responsible for the creation of optical packets and the BMT, at the edges of the optical network. Finally, at the optical technology level, the challenges are quite important since the building of large optical switches or advanced optical packet add/drop multiplexers requires a high level of integration of the technology and a low cost packaging to be competitive with respect to electronics.

Due to the asynchronous nature of the packet stream at the reception side, a specific receiver has to be designed able to receive packets that can experience packet-by-packet power variations and packet-by-packet phase fluctuations. Fig. 10 shows a 10 Gb/s BMT capable to cope with 14 dB of power variations (electrical) between consecutive packets.

For the WAN the basic building block is an optical packet space switch offering capacities of several Terabit/s. To realize such a switch, the DAVID project focuses on SOA technology,

which today represents an interesting alternative because it is the only technology capable of providing all the required specifications [i.e., high ON/OFF ratio, fast switching time, low polarization sensitivity, WDM compatibility simple to implement, robustness (exploitation of the carrier density)]. As a first step of integration, the objective is then to build and test a SOA gate arrays module. Fig. 11 shows a highly integrated 32 SOA module [3], including its driving electronics and exploiting self-aligned flip chip assembly of SOA arrays on silicon submounts [46].

In addition to this, and in the perspective of an all-optical packet switching concept (as proposed in the DAVID project), regeneration is mandatory to enable the cascading of OPRs. The SOA-based Mach-Zehnder interferometer (MZI) has been demonstrated as a key element for the regeneration [38]. Fig. 12 shows a 3R-regenerator architecture validated at 40 Gb/s with integrated SOA-based MZI.

In the case of a MAN using a basic optical packet add and drop structure as it is proposed in the frame of the DAVID project for a cost saving introduction of an optical technology, there is no need for a specific development. We, thus, need only burst mode transmitters, based on traditional low cost integrated laser modulators (ILM) gated by a simple SOA gate, and burst mode receivers. The burst mode transmitter has been experimentally validated showing no significant penalty with respect to the ILM only considering transmission distances compatible with metro needs [40].

However, if we want to increase the performance of the concept by introducing more flexibility at the optical level, then tunable elements are mandatory like, e.g., a monolithically integrated wavelength selector as experimentally validated in [41].

### B. Electronic Technology and Building Blocks

Necessary switching and routing functions, such as header recognition and delineation, data processing, table lookup or bit level synchronization, for instance, but also many interface operations (e.g., between nonoptical legacy networks), cannot solely (or only with insufficient performance) be carried out by pure optical means, at least in the near and mid term future. So, even in an optical network, electronics will be widely deployed in addition to advanced optical switching technologies. The project integrates the advantages of both technologies in a complementing manner and functional split.

The main electronic blocks of the metro ring node, that is the traffic manager board (TMB; including MAC controller) and the BMT, take over all functions needed to interconnect the OPADM and the client layer, which are listed next.

#### *Traffic from client layer to OPADM (DAVID Packet Add).*

- Overhead processing of legacy traffic (e.g., IP headers). L3 routing functions, if required.
- Aggregation of legacy traffic with common attributes as destination, class of service (CoS), QoS, etc.;
- Burstification to build packets according to the DAVID packet format and segmentation (if required) to optimize the filling ratio of the optical packet payloads;
- Queuing/buffering in various queues to differentiate packets according to different possible destinations and/or priorities, etc.;

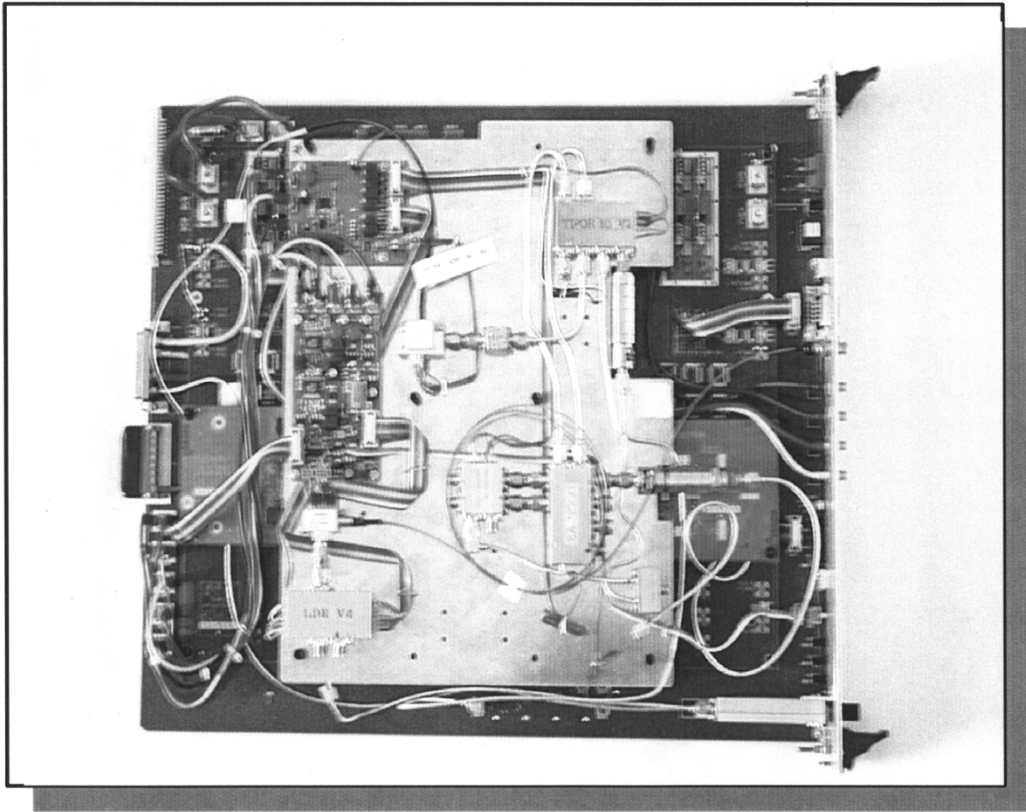


Fig. 10. Photo of a BMT including the mux and demux part.

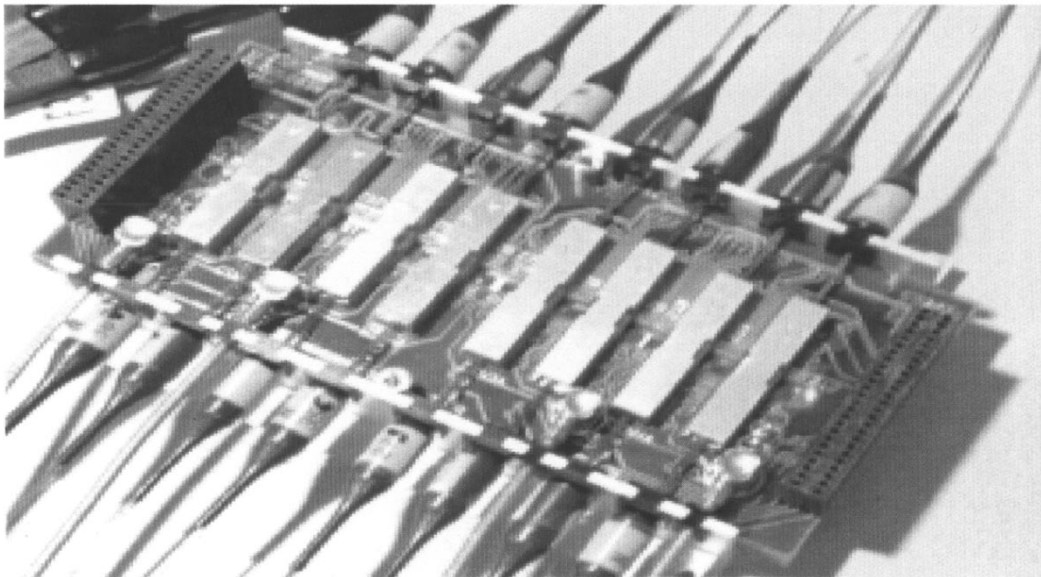


Fig. 11. Photo of a 32 SOA module.

- MAC to control the access to/from the optical Metro ring (separate MAC channel; MAC controller); separate transport of packet overhead in the MAN;
  - Load balancing to spread the load over accessible wavelengths and/or optical bands (MAC controlled selection of transmission wavelength at or after E/O conversion);
- Traffic from OPADM to client layer (DAVID Packet Drop).*
- Burst mode reception of optical packets at the BMT after O/E conversion; bit level synchronization and clock re-

- covery; preamble detection; drop function toward TMB (including bitrate adaptation);
- Extraction of client traffic from the payloads of the optical packets; recovery of, e.g., IP packets (using appropriate buffer tools); reassembly (if required);
- Addressing of the client traffic (e.g., IP packets) to the correct destination port/legacy interface;
- Transmission to the client layer (synchronized with client layer, if required; using, e.g., FIFO buffers).

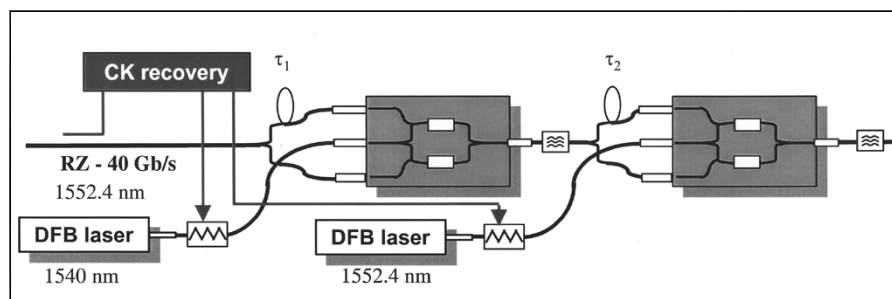


Fig. 12. 3G-regenerator architecture using SOA-based MZI.

### 1) Functional Overview of the BMT

The BMT is the intermediate block between optical network components (e.g., OPADM) and TMBs and presently is designed to process one single 10 Gb/s data channel (wavelength) running with a continuous stream of bursts (slots). For that purpose some specific functions have to be implemented in a BMT.

*Optical/Electrical Conversion (O/E, E/O)* at the input/output of the data channel (NRZ signal format). High-input receiver sensitivity is prerequisite to cope with possibly low optical power at specific nodes.

*Clock and Data Recovery (CDR)* to extract the bit clock of incoming 10 Gb/s bursts (slots), amplify and equalize the signal amplitude, detect start of slot, and finally to synchronize overhead and payload bits with the extracted clock. Especially for clock recovery and signal amplitude equalization new fast electronic approaches (e.g., in SiGe technology) are required as conventional PLL and AGC techniques, respectively, prove to be too slow for such applications.

*Framer Board* to implement the slot/packet Add/Drop functionality. It is connected to the DAVID network by means of 10 Gb/s SERDES interfaces and to the TMB via 2.5 Gb/s Add/Drop parallel interfaces.

Regarding the MAN part of the DAVID network, one additional BMT per node is needed to receive the MAC channel. Buffering and priority scheduling of slots to be added is managed by the MAC controller and performed in the TMB.

### 2) Functional Overview of the TMB

A number of major functions the TMB needs to use in a metro ring node can be outlined:

- *Buffer controller* stores the packets going toward the MAN ring according to priority and destination. It keeps the MAC controller informed about packets in the buffer each time a packet is stored in the buffer. The MAC controller informs the buffer controller when it must forward a packet toward the BMT and metro ring.
- *MAC controller* terminates and regenerates the MAC packets travelling on the MAC channel.
- *Legacy networks controller* stores packets destined for the legacy network interfaces (one or more). Flow control from any legacy network controller has to be taken into account for this purpose.

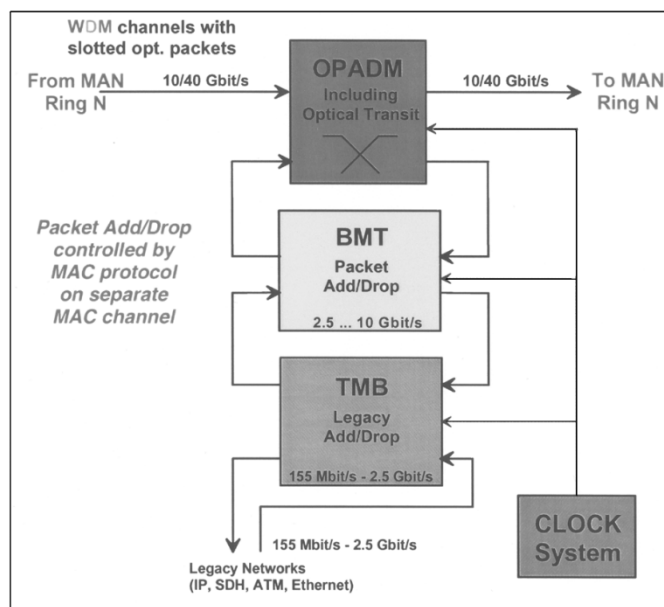


Fig. 13. Basic outline of a DAVID metro ring node.

## VII. TRAFFIC AND PERFORMANCE ASPECTS

The traffic sources relevant to the DAVID project are traffic multiplex collected from legacy networks by routers and/or switches that interface with the backbone for high speed and long distance site to site interconnection. It is unlikely that the single application or the single user terminal will have direct access to the network. As a consequence traffic analysis and modeling should be kept as general as possible, by means of a few, general theoretical traffic models.

*Man Performance:* The main issues to address regarding the performance of the DAVID metro network are the achievable *throughput* and the *fairness*. As usual in multiaccess protocols, some overhead is necessary to perform access control. The more the throughput is close to one (the ideal value) the better the MAC protocol. This is not enough because we also want the MAC protocol to share as evenly as possible the bandwidth between the nodes. For a multiring architecture several solutions have been proposed and investigated in the project and here, as an example, we present results referring to the multi-SAT access control scheme described in Section VII.

In Fig. 16, the throughput per node is plotted against the number of nodes active on the ring for the case of a MAN with



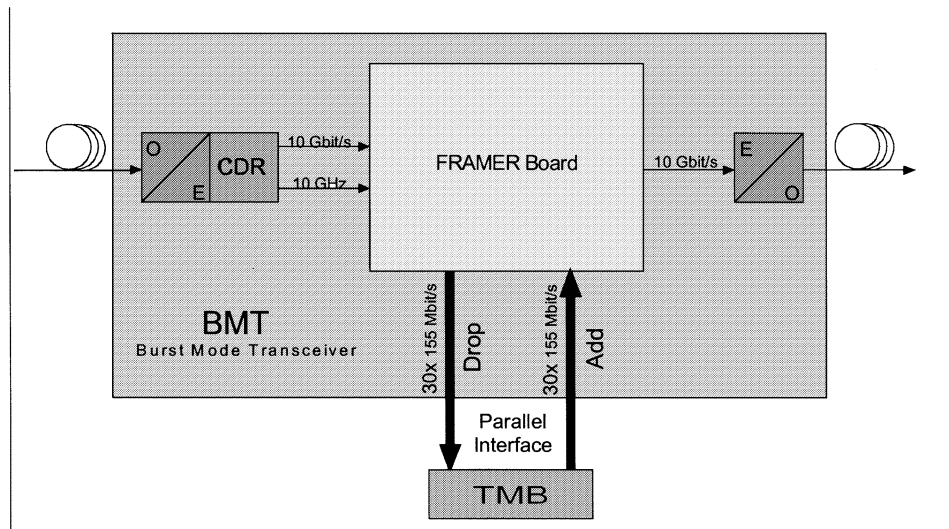


Fig. 14. BMT connected with TMB.

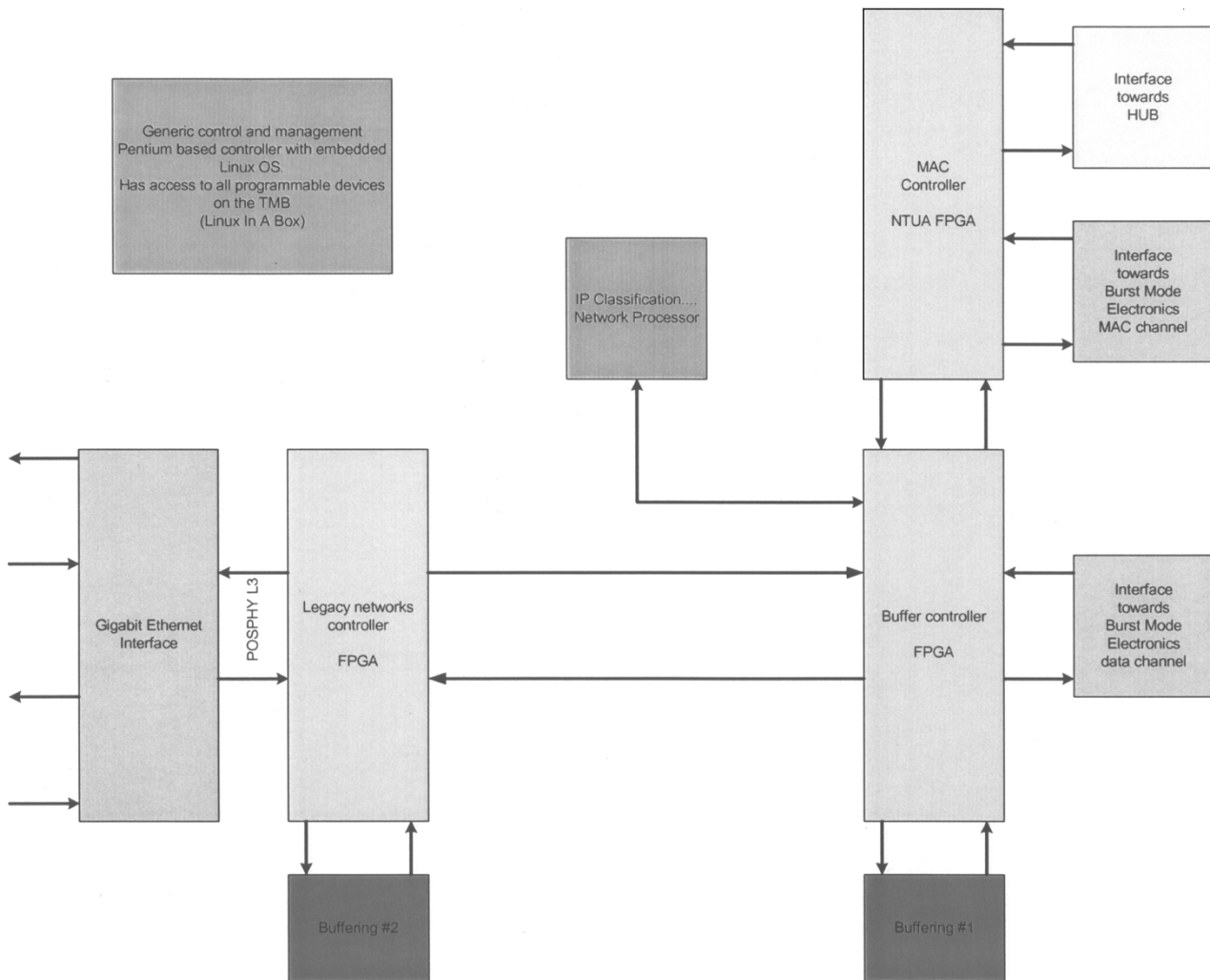


Fig. 15. Functional blocks of the TMB.

16 logical rings with 10 nodes and 16 + 1 wavelengths per ring. The packet slot is set to 1  $\mu$ s and the size of the rings is such that the round-trip time (RTT) is equal to 0.5 ms (that is 500 slots). Two cases have been simulated with the SAT quota set

at  $Q = 100$  and  $Q = 500$ . The traffic scenario consisted of IP traffic sources generating fix length optical packets according a Bernoulli distribution. The traffic is intraring with a load of 0.7 per ring, and node unbalanced: all nodes send packets only

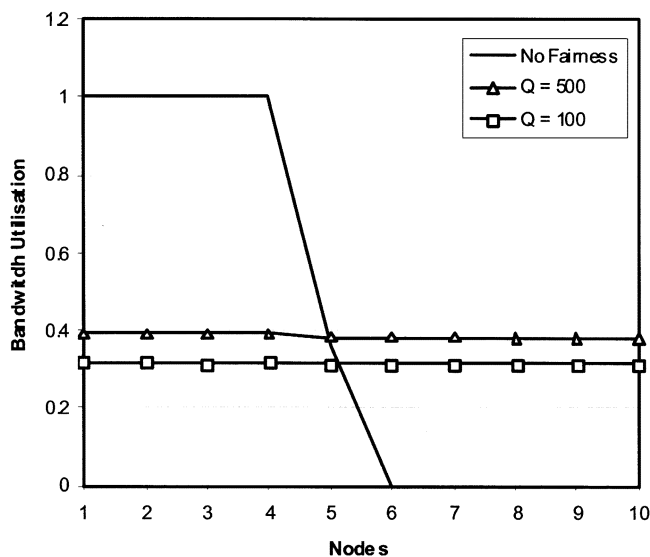


Fig. 16. Intring traffic; relative throughput per node for total load on the ring of 0.7, without fairness control (solid line) and with SAT for two values of  $Q$ .

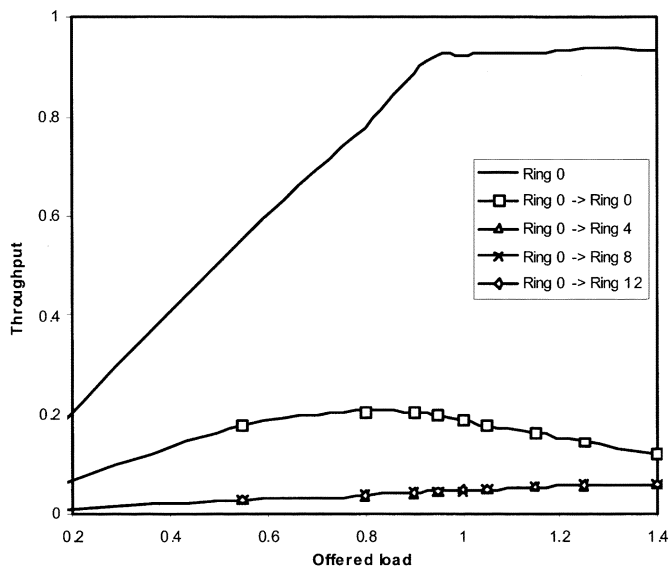


Fig. 17. Interring MAN throughput with unbalanced traffic; overall ring 0 throughput (solid line) and interring throughput (marked lines) as a function of the total traffic load.

to node 0 of ring 0, except node 0 of ring 0 that sends packets uniformly to the rest of nodes of ring 0. As expected without fairness control (solid line), the bandwidth utilization is *unfair*: upstream nodes (node 1, 2, 3, 4, and partially the node 5) use all empty slots (the relative throughput is one) and the downstream nodes (node 6, 7, 8, 9, and 10) cannot transmit (the used bandwidth is zero). By introducing the fairness control the bandwidth utilization becomes *fair* both for the case  $Q = 500$  (triangle markers) and  $Q = 100$  (square markers).

The fairness problem for interring communications is addressed in Fig. 17. Here, an unbalanced interring traffic matrix is considered, where about 30% of the traffic is intraring while the remaining 70% is evenly spread among the remaining rings, and per-ring uniformly distributed among the nodes.

Under the traffic conditions used to obtain Fig. 17, also the benefits of exploiting the spatial reuse in the MAC protocol was

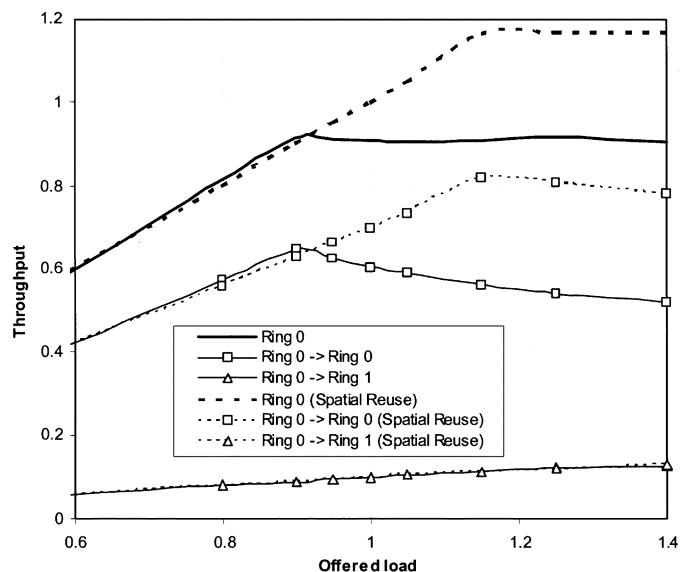


Fig. 18. Interring MAN throughput under unbalanced traffic, overall ring 0 throughput: with spatial reuse (dashed line), without spatial reuse (solid line), as a function of the total traffic load.

studied varying the number rings from 4 to 16. Fig. 18 shows the throughput with (dashed line) and without (solid line) exploiting the spatial reuse for a four rings MAN. As expected, the higher the percentage of intraring traffic the more the gain of performance due to the spatial reuse. This is more evident in small networks (low number of rings).

Results regarding the performance of MAC protocols able to differentiate the QoS between traffic streams and to guarantee some given performance to real time traffic are currently under investigation, as variation of the basic protocols here described.

**OPR Performance:** Within DAVID the effectiveness of congestion resolution schemes in the OPR has been analyzed for FLP and SVLP. The OPR control logic performs the following function:

- *forwarding*: decide first to which fiber the packet has to be sent, in accordance with the routing table;
- *wavelength allocation*: select the wavelength, among the  $w$  available on the fiber, in order to minimize congestion (at most  $w$  packet may be transmitted on a given fiber at a given instant);
- *delay allocation*: in case no wavelength is available choose the fiber delay line to sent the packet.

The results regarding wavelength allocation presented in Fig. 19 refer to the algorithms studied in [33], applied to the DAVID scenario. Without loss of generality the average packet (train of slots) length is assumed to be unit and the slot is set to 0.2 (on average five slots per packet). The switching matrix has  $M = 4$ ,  $w = 16$ , and no recirculation of packets in the buffer are allowed. The curves show that there is an optimal value of the delay unit ( $D$ ), placed around one, and that the wavelength allocation algorithms have a huge influence on performance. A purely random or round-robin choice of the output wavelength bring to a very high-packet loss probability. Smarter algorithms, such as that choosing the wavelength with the shortest queue (Minl) or that with the minimum gap between packets (Ming), improve the performance of several

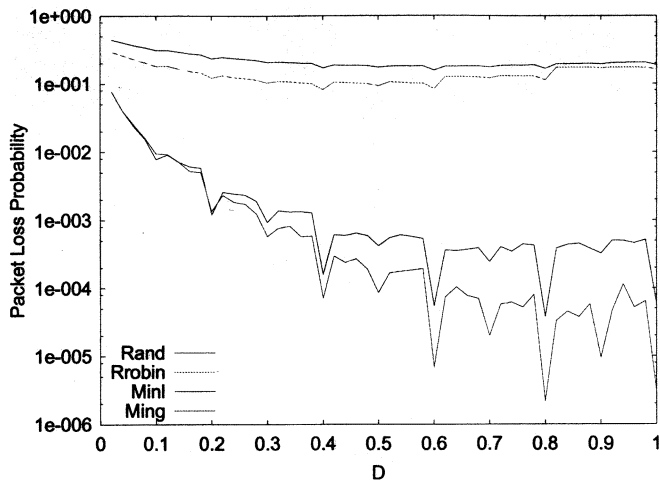


Fig. 19. SVLP: performance comparison of several wavelength allocation algorithms, as a function of the increasing rate of the FDLs, for a switching matrix with  $M = 4$ ,  $w = 16$ ,  $B = 4$  and load 0.9.

orders of magnitude at the expense of a very limited increase in the computational complexity [33].

Regarding the delay allocation, the first issue to address is whether a F-FDL or an I-FDL architecture can be adopted. F-FDL appears simpler to control and, in principle, should perform similarly to I-FDL because, by using recirculation of packets, variable delays are achievable. Unfortunately, this is only partially true. Fixed parameters  $B$  and  $k$  (number of wavelength per FDL), the product  $B \times k$  puts an upper limit on the number of packet that may present in the buffer at a given time. Therefore,  $P = B \times k$  measures the number of “places” in the buffer. Obviously, a packet needing a long delay will circulate in the buffer more than once and, therefore, use buffer places. Therefore, for a given  $P$ , we expect better performance from a I-FDL buffer because packets will recirculate less and use less places. This is confirmed by Fig. 20 for FLP, where it is shown that to obtain the same performance a F-FDL buffer would require many more wavelengths, meaning, at the least, a larger hardware cost. For SVLP again the analysis is more complex but the results are similar.

### VIII. NETWORK MANAGEMENT ISSUES

The work carried out on network management stresses the service-centric perspective of an optical transport network, which is tailored to a packet transporting and/or switching capability while preserving circuit-based service provisioning. The focus has been put on four main aspects: 1) provide a centralized functional model; 2) define a control channel; 3) performance monitoring and network resilience; and 4) QoS impact on management.

For the functional model of an optical packet transport network (OPTN) as proposed by the DAVID consortium, two approaches can be taken: the first is the optical transparent version, meaning that the payload is transparently switched; the second is the opaque approach implying that the payload of each packet at every wavelength is terminated at each single node. The former requires advanced optical components like, e.g., fast

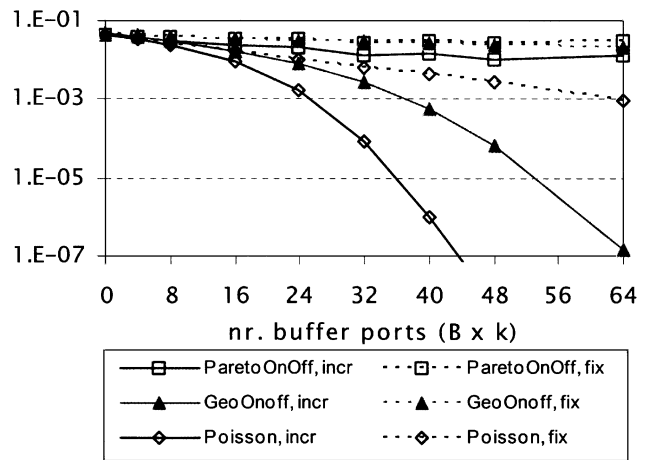


Fig. 20. FLP: performance comparison of F-FDL and I-FDL optical buffers as a function of the number of buffer places  $B \times k$ , for a switching matrix with  $M = 6$  and  $w = 32$ .

optical switches and, hence, the latter is considered to suit best at least in the short term (or intermediate) solution.

The OPTN is able to support wavelengths, as well as optical packets. Therefore, the architecture specified in the ITU-T Recommendation G.872 [1] has been taken as a starting point to construct a model incorporating the extra dimension of multiplexing introduced by subdividing each wavelength into a stream of packets. OPS capability can be modeled as a new independent layer or as a so-called sublayer, which amounts to enhancing one of the three defined layers in [43]. The latter is preferred because the existing architecture can be maintained avoiding additional efforts in defining new management interfaces. Extending G.872 to OPS can be done by adding two sub-layers within the optical channel layer (OCh): an optical packet (OPA) sublayer which has an ingress–egress view within the OPTN, where any of them can be an interdomain access point, and an optical packet section monitoring sublayer, which performs section monitoring between two adjacent OPTN nodes. These functional layered models require a centralized network management system. The effects a decentralised system would have on the layered model, e.g., using a separate protocol for exchange and update of routing information’s to setup and release paths across the OPTN, is not subject of discussion in this paper.

Additionally, the optical supervisory channel (OSC) in [1] needs to be extended to both new optical packet sublayers, where processing is done in the electronic domain. In case 3R-regeneration is done electrically, the tandem connection monitoring (TCM) and digital channel (DCH) sublayers cannot be eliminated, since it will also be necessary in the optical packet network, either on a link basis (span by span; TCM) or end-to-end (DCH). Only if all-optical 3R-regeneration can be deployed, these TCM and DCH sublayers are redundant and this functionality could now be modeled as part of the adaptation function between OCh and OPA sublayers.

Network resilience is a critical functional area that needs fully exploitation of the control channel to detect network failures and undertake recovery actions such as, e.g., reroute traffic crossing the failed network element. The detection of failures is part of

performance Monitoring that needs to be extended compared with circuit-switched WDM networks because of the specific equipment used in the OPTN (e.g., SOAs, burst transmitters). The service recovery response is dependent on its place of occurrence: in the WAN, which is a meshed network, classical GMPLS schemes such as local or path protection can be deployed, while in the MAN ring-based schemes are more appropriate. Within the DAVID project, different protection strategies are discussed and evaluated in terms of both cost and complexity.

The OPTN is aimed at transporting different types of services with guaranteed QoS and, therefore, its impact onto service management is an important topic also addressed. There exist a legal contract frame between a service provider and a customer called service-related level agreement hierarchy (SAH) that sets QoS expectations in terms of network levels like throughput, loss rate, delays, etc., and times of availability, method of measurement, pricing, as well as the consequences when QoS levels are not achieved. DAVID network encompasses both packet and circuit based services, where customers expect end-to-end, measurable, formalized, and guaranteed services that can be offered through a SAH. QoS dimensions are abstract characterizations of requirements and QoS management is the concrete realization of the required quality level for services in a real system. This is commonly translated into a Service Level Agreement (SLA) and a Service Level Specification (SLS) that fall into the frame of the SAH.

#### IX. PROSPECTIVE ISSUES

The scope of the IST-DAVID project is twofold. First, to present and validate a concept allowing dynamically reconfigurable optical packet networks. Second, to identify and present advanced concepts having the potential to alleviate more general and complex optical packet switching problems and to study alternative technologies and implementation methods. However, these potential solutions are naturally not mature yet and, hence, they require further investigation. In this context, the prospective studies address two thematic clusters. The first cluster aims at identifying novel transportation and signaling formats, as well as alternative information processing methods. The second cluster aims at investigating alternative networking concepts and system architectures.

Within the first theme, the issue of identifying the most suitable transportation and signaling format is central. This format not only has a direct impact on the attainable level of integration between the IP and the WDM control planes but also it determines the amount of information that could be exchanged between nodes, as well as the frequency of updating this information. The latter two issues are also related to the more general problem of "processing bottleneck." This has its origin in the fact that the currently available electronic systems are struggling to cope with information processing requirements at the transmission line rate of 10 Gb/s, for capacities approaching or exceeding few hundreds of Gigabit/s.

The IST-DAVID tackles the "processing bottleneck" problem from different perspectives. The straightforward approach is to develop 40 Gb/s electronic processing systems based on

SiGe technology needed for any function that requires bit level synchronization (e.g., clock and data recovery, CDR), as well as for table lookup, header processing, burstification of data and the implementation of various control elements. Alternatively, still under the framework of information processing based on electronic devices, two approaches are examined. When multilevel ( $M$ -ary) coding principles based on a combination of wavelength and time are adopted, electronic processing could be carried out at a lower speed without compromising the overall information transfer rate. At the same time, the subsequent multiwavelength label/header allows forming an out-of-band signaling mechanism compatible with GMPLS requirements [1], [2]. The second approach is complementary to the previous one demonstrating a  $N \times 40$  Gb/s transportation and switching scheme where each single wavelength 40 Gb/s high speed channel is decomposed into a group of WDM channels adopting the bit-parallel transmission principle [3].

#### X. CONCLUSION

This paper has been titled "A Viable Approach Toward Optical Packet Switching" because the DAVID project is not only about developing a final solution but also to provide a path toward it. The project has taken a very pragmatic approach in which optical and electronic technologies are combined in a way that exploits the different technologies in the best way in the current state. This holds true for both the shorter and the longer-term approaches.

The project has been strongly focused on the concept and the migration path, but is full aware that a number of things need to be further enhanced to enable a cost effective introduction of optical packet switching. This specifically concerns the optical component technology that today mainly has been driven by the transmissions applications rather than networking. The project has identified that such initiatives have to be taken to improve the level of integration and reduce the cost in packaging, etc.

With this in mind the DAVID project believes that the optical packet switching option is viable and that the DAVID concept is a strong candidate. The approach has been carefully analyzed in a holistic way both theoretically and through a concept demonstrator. Throughout the project the concepts of both the WAN and the MAN parts have been adjusted according to results and observations. In this way, the DAVID project provides both a viable and a validated approach toward optical packet networks.

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**W. Koerber** was born in Stuttgart, Germany, on July 10, 1956. He received the diploma and Ph.D. degree in physics from the University of Stuttgart, Stuttgart, Germany, in 1982 and 1988, respectively.

In 1988, he joined Alcatel Research, Stuttgart, Germany, where he was in charge of LPE- and MOVPE-growth and design of components for optoelectronic transmission systems and OEICs. Since 1997, his work has focused on design and standardization of HFR and HFC access network systems. Presently, his activities are dealing with

networking concepts and protocols for optoelectronic metro and core networks, especially for optical burst transmission. This work includes also network management aspects.



**A. Stavdas** received the B.Sc. degree in physics from the University of Athens, Athens, Greece, the M.Sc. degree in optoelectronics and laser devices from Heriot-Watt University, Edinburgh, U.K./St. Andrews University, and the Ph.D. degree from the University College of London, London, U.K., in the field of wavelength routed WDM networks.

Currently, he is Principal Researcher of ICCS, NTUA, and he is heading the Optical Networking Group of NTUA (<http://www.ong.ece.ntua.gr>).

He is the author or coauthor of over 50 journal publications and conference articles. He worked in a number of European Projects like IST-DAVID, IST-GIANT, IST-OLYMPIC, AC069 COBNET, and AC050 PLANET. He also led projects funded by industry (ULTRA funded by Nortel Networks and Thermo\_G funded by Thermophotonics). Current interests include physical layer modeling of optical networks, optical packet switching, ultra-high capacity end-to-end optical networks, OXC architectures, and WDM access networks.

Dr. Stavdas served as Chairman of the Optical Network Design and Modeling Conference (ONDM 2000) and as a Member of the Technical Committee for Conferences like GLOBECOM and Photonics in Switching.

**M. Renaud** was born in France, in 1960. She received the engineer diploma and the Ph.D. degree from Institut National des Sciences Appliquées, Lyon, in 1983 and 1985, respectively.

In 1985, she joined Laboratoires d'Electronique Philips, where her fields of interest were Physics and Technology of III-V semiconductor microelectronics and integrated optics. Since July 1991, she joined Alcatel, Marcoussis, France, and has been engaged in research on InP based photonic devices for optical signal processing including switching, wavelength conversion, regeneration, etc. She is currently leading a group on hybrid and integrated components. She has been involved in several European projects (RACE, ACTS, and IST) and has in particular coordinated the ACTS AC043 project KEOPS (KEys to Optical Packet Switching). She has contributed to about 100 papers in international journals and conferences. She has participated in various conference program committees, including OFC, ECIO, CLEO-E, and OAA.



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While at UPC, his research interests included WDM networks, cross-connect architectures, optical signal impairments, network management, and optical control plane. In April 2001, he joined BT in Martlesham Heath, U.K., where he has been working in BTextact in the areas of design, development, and consultancy on optical networks.



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**N. Leligou** received the Dipl.-Ing. degree in electrical and computer engineering in 1995 and the Ph.D. degree in broadband networks from the National Technical University of Athens (NTUA), Athens, Greece. Her Ph.D. thesis was in the area of access control mechanisms in broadband networks.

Her research interests include the design and implementation of scheduling components for protocol processor environments, MAC protocols for HFC and PON systems, and access mechanisms for high-speed networks. She is currently investigating

access control mechanisms for packet-oriented Gigabit PONs.



**Lars Dembeck** studied electrical engineering with the main focus on communications engineering and graduated in 1988.

After joining Alcatel, Research and Innovation, Stuttgart, Germany, he worked on development and implementation of novel electronics for optical network elements in several field trials, as well as on the design of concepts and management for photonic networks. He currently is responsible for multiservice core switching platforms within Alcatel, Research and Innovation. He has been

involved in many national and EC projects (BMBF Photonik I/II, KomNet, RACE ATMOS, ACTS MEPHISTO, ACTS PELICAN).



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From 1998 to 2000, he was working as a Researcher at COM, Technical University of Denmark, Lyngby, Denmark. His main interest is in investigation and design of large-scale networks and electronics with attention paid to physical limitations combining electronics and optical components for new network node designs. In the DAVID project, he is responsible for the gateway design.



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**N. Le Sauze** was born in Quimper, France, in 1974. He received the degree in physics from the Université de Bretagne Occidentale, Brest, France, in 1996, and the engineer diploma of telecommunication from the Ecole Nationale Supérieure des Télécommunications de Bretagne, Brest, France, in 1998.

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**M. Mahony** was born on August 28, 1944. He graduated from Essex University, Colchester, U.K., in 1974 and received the Ph.D. degree in research in digital transmission systems, in 1977.

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He is also Head of the Photonic Networks Laboratory, which is focused on the study and design of photonic networks and the chief investigator for grants supported by industry, EPSRC and the EC. The main current area of interest is in understanding the physical limitations associated with the realization of optical transport networks.

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He then joined Alcatel, Research and Innovation, Stuttgart, Germany, where he is responsible for the optical systems and networks activities. He has authored many technical papers on electronic and optical broadband telecommunications and holds several patents. Since 1985, he has been involved in various national and EC projects (BMBF Photonic I/II, KomNet, RACE ATD, RACE EXPLOIT, RACE OSCAR, RACE ATMOS, ACTS MEPHISTO, ACTS PELICAN).